zoopa Q Evo 550

QUICKLAUNCH

Start

Before start, definitely make sure that sufficient GPS satellites are available. As soon as the blue LED inside the GPS Tower starts to flash, sufficient signals have been allocated. The longer you wait, the more signals will be found! This will clearly increase your flightexperience.

Please proceed as described:

-Set both upper switches on the controller (left and right) to „0". To start the motors, pull down the left control stick into the right corner and wait for the motors to start. Then release the stick, so it returns into center position.

-Now switch to GPS Mode by setting the left switch to 0 and the right switch to 1. Carefully push the left stick up. The model will slowly take off.

Important GPS- Mode note!

If you notice that the quadrocopter holds the position unreliably in GPS Mode, we recommend to lift it it up to 30m height and let it fly in squares for 2 minutes . During this time, the quadrocopter will automatically correct its GPS and compass values. A reliable position hold will be the final result.

In Return Home Mode, the quadrocopter rises onto 35m, in Fence- Mode on up to 100m height.

If you have any further questions, please contact our service:

<div align="center">

Service & Support
ACME the game company GmbH
Boikweg 24
33129 Delbrück Germany
Telefon: +49 2944 9738 30
E-Mail: service@ACME-online.de
http://www.ACME-online.de

</div>

ACME
the game company

QUICKLAUNCH

Start

Before start, definitely make sure that sufficient GPS satellites are available. As soon as the blue LED inside the GPS Tower starts to flash, sufficient signals have been allocated. The longer you wait, the more signals will be found! This will clearly increase your flightexperience.

Please proceed as described:

-Set both upper switches on the controller (left and right) to „0". To start the motors, pull down the left control stick into the right corner and wait for the motors to start. Then release the stick, so it returns into center position.

-Now switch to GPS Mode by setting the left switch to 0 and the right switch to 1. Carefully push the left stick up. The model will slowly take off.

Important GPS- Mode note!

If you notice that the quadrocopter holds the position unreliably in GPS Mode, we recommend to lift it it up to 30m height and let it fly in squares for 2 minutes . During this time, the quadrocopter will automatically correct its GPS and compass values. A reliable position hold will be the final result.

In Return Home Mode, the quadrocopter rises onto 35m, in Fence- Mode on up to 100m height.

If you have any further questions, please contact our service: